TOSHIBA Bi-CMOS Integrated Circuit Silicon Monolithic

# **TB62D786FTG**

#### 9-channel constant current LED driver with 1wire

The TB62D786FTG is a constant current driver designed for LED and LED illumination.

The TB62D786FTG incorporates 9-channel of 7-bit PWM dimming controllers and constant current drivers. 9 constant current drivers are divided into three blocks, each consisting of three drivers, and the output current of each can be independently adjusted by the relevant external resistor.

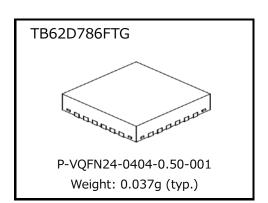
The TB62D786FTG is controlled using the only DATA-IN input signal. (with operate high speed data transfer)

The TB62D786FTG can be set address with ID pin.

(Up to 64 address)

The TB62D786FTG include regulator and the regulator convert a power supply of LED to a power supply of IC circuit.

Additionally, data can be transferred at high speed with Bi-CMOS process.



### **Feature**

• Power supply voltage : VL = 7.0 to 28V (The case used only by a power supply of LED)

 $Vcc = 5.0V \pm 10\%$  (The case that the power supply of LED and that of this IC separately. )

• Output drive capability: 80mA (max)  $\times$  9 channels

• Constant current output range: 5 to 40 mA

Voltage applied to constant current output pins: 0.4 V(min) @I<sub>OUT</sub>=5 to 40 mA

Designed for common-anode LEDs.

The input interface is controlled by DATA-IN (1-wire)

• Thermal shut down (TSD) included.

Input and output of logic circuit: 5V CMOS Interface

(Schmitt trigger input)

Maximum output voltage: 28 VPWM control circuit included: 7bit PWM

Driver identification:
 Up to 64 drivers can be controlled individually

• Operating temperature range:  $T_{opr} = -40 \text{ to } 85^{\circ}\text{C}$ 

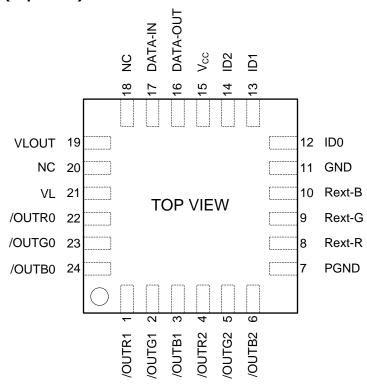
• Package: P-VQFN24-0404-0.50-001

Constant current accuracy

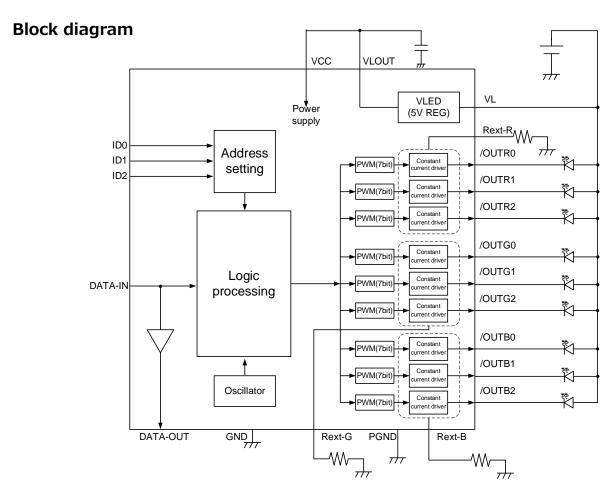
Output voltage	Current accuracy between channels	Current accuracy between ICs	Output current	
0.5 V	±3.0%	±6.0%	15mA	

This product is very delicate because of elements of MOS structure. In handling, please take care of measures of static electricity, such as use of a ground band or an electric conduction mat, removal of static electricity by an ionizer, and management of temperature and humidity.

### Pin Assignment (top view)



Please be sure to connect the back radiation PAD of a QFN package to GND of a substrate.



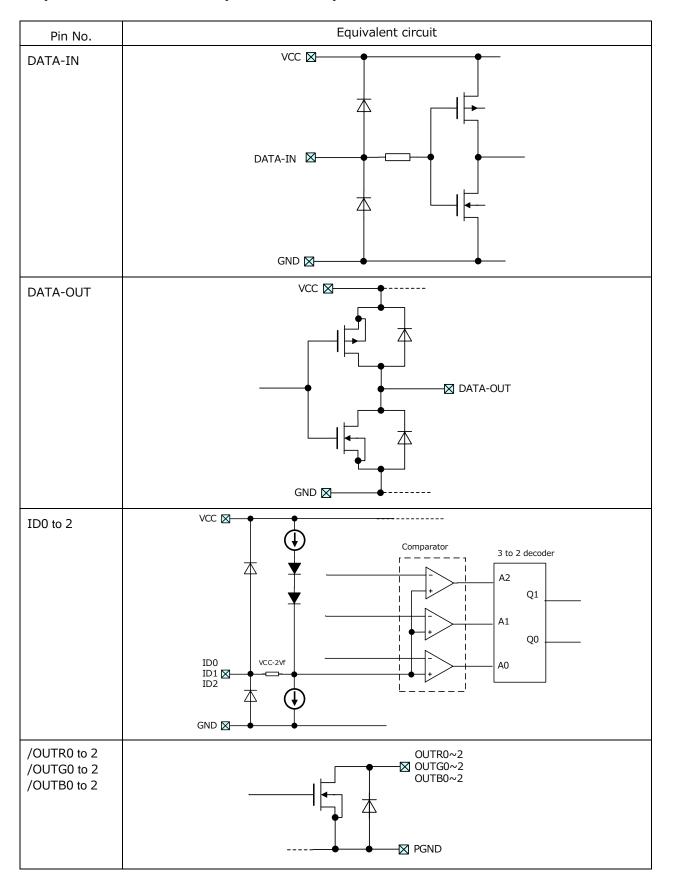
Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

# **Pin Description**

Pin No.	Symbol	Function
1	/OUTR1	Constant current output pin. (Open-drain type)
2	/OUTG1	Constant current output pin. (Open-drain type)
3	/OUTB1	Constant current output pin. (Open-drain type)
4	/OUTR2	Constant current output pin. (Open-drain type)
5	/OUTG2	Constant current output pin. (Open-drain type)
6	/OUTB2	Constant current output pin. (Open-drain type)
7	PGND	Power ground pin
8	Rext—R	External resistor pin for output current configuration (/OUTR0, /OUTR1, /OUTR2)
9	Rext-G	External resistor pin for output current configuration (/OUTG0, /OUTG1, /OUTG2)
10	Rext-B	External resistor pin for output current configuration (/OUTB0, /OUTB1, /OUTB2)
11	GND	Ground pin
12	ID0	ID configuration pin
13	ID1	ID configuration pin
14	ID2	ID configuration pin
15	Vcc	Power supply pin (5V)
16	DATA-OUT	Serial data output pin (Data buffer of DATA-IN)
17	DATA-IN	DATA input pin
18	NC	Non-connection pin. Please connect to GND or Vcc.
19	VLOUT	5V Regulator output pin. Please connect VLOUT and Vcc when it use included regulator. In case it inputs 5V direct to Vcc pin please VLOUT connect to GND pin.
20	NC	Non-connection pin. Please connect to GND or open. *Note 1
21	VL	Power supply voltage (LED power supply)
22	/OUTR0	Constant current output pin. (Open-drain type)
23	/OUTG0	Constant current output pin. (Open-drain type)
24	/OUTB0	Constant current output pin. (Open-drain type)

<sup>\*</sup>Note 1) Please warn a next pin shortstop when connecting 20 pins to GND.

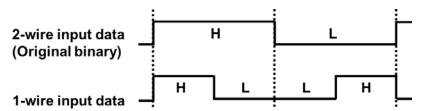
# **Equivalent circuit for inputs and outputs**



The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

### **Programming the TB62D786FTG**

This product is controlled with 1-wire data signal. As compared with 2-wire data signal synchronous with the clock signal in conventional products, this product assigns each data state to the transition state (H to L or L to H) as shown below.



For setting data, select from (2) normal programming mode or (3) special mode at (1) data setting format. If all outputs are controlled, (3) special mode is recommended.

#### (1) Data setting format

Each command setting input to DATA-IN is set with the following format.

This product recognizes the command frequency (1-bit data width) by taking in the start command (the start condition of data input).

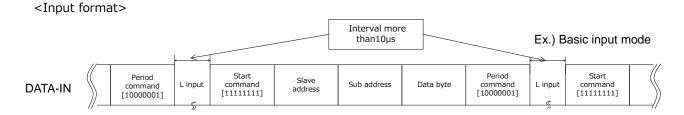
Start command: 1010101010101010 (original binary: 11111111)

Since this product continues to recognize the signal interval which recognizes at the start command until the period command, input the pulse width in 1 bit within 50% duty so that the period is not collapsed until completion of the period command.

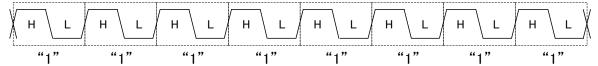
(Refer to Operating Ranges.)

Period command: 1001010101010101 (original binary: 10000001)

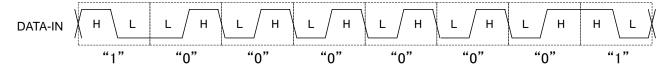
After the completion of the period command input, make sure to set the interval ("L") more than 10  $\mu$ s until next start command input.

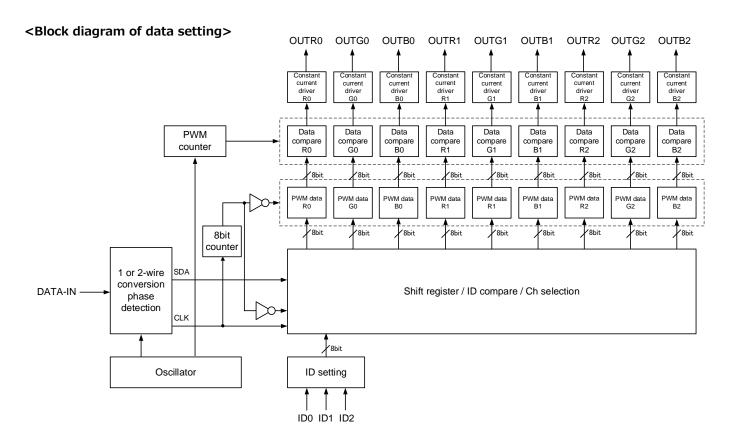


Example 1) Start command setting [original binary 11111111]



Example 2) Period command setting [original binary 10000001]





(2) Serial packet format in normal programming mode

Normal programming mode should be set as the following flow.

Start command -> Slave address -> Sub-address -> Data byte -> Period Command Slave address: ID of IC, Sub-address: set to Output channel, Data byte: setting PWM

Interval ("L" more than 10µs)	Start Command	Slave Address	Sub-address (channel select)	Data byte (PWM configuration)	Period Command	Interval ("L" more than 10µs)
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(3) Serial packet format in special mode

This is how to set when all channels are set individually.

-Special mode setting (In the case that all channels are set individually)

If the Special mode is set to sub-address, the illuminating data of all channels can be set.

Special mode: 0110100101010101=0x6955 (original binary: 01100000)

†	Interval ("L" more than 10µs)	Star Comm	_	Slave ddress	Sub-address (Special mode)		Data OUTR0	Data OUTG0	Data OUTB0
	Data OUTR1	Data OUTG1	Data OUTB1	Data OUTR2	Data OUTG2	Data OUTB2	Perio Comm		

In case the data (more than 9 channels) provided the 10<sup>th</sup> and subsequent data are treated as invalid.

-Channel setting to be output

Start Command	Slave	Sub-address	Data setting	Period Command
	Address	(channel setting)	(Output which is set at	
			sub-address)	



### (4)Data settings

a) Slave address

Input voltages and logic states of the ID0, ID1, ID2 pins are determined as follows. (High order bit="0", Low order bit =0 (Except of all selections)) Vcc="1010"=0xA, open="1001"=0x9, Rext-R/B/G(\*)="0110"=0x6, GND="0101"=0x5

Slave setting

Slave setting					
Slave addre	SS	Original	ID2	ID1	ID0
Input with one wire	Hexadecimal	binary			
0101010101010101	0x5555	00000000	GND	GND	GND
0101010101011001	0x5559	00000010	GND	GND	Rext-R/G/B*
0101010101100101	0x5565	00000100	GND	GND	Open
0101010101101001	0x5569	00000110	GND	GND	Vcc
0101010110010101	0x5595	00001000	GND	Rext-R/G/B*	GND
0101010110011001	0x5599	00001010	GND	Rext-R/G/B*	Rext-R,G,B*
0101010110100101	0x55A5	00001100	GND	Rext-R/G/B*	Open
0101010110101001	0x55A9	00001110	GND	Rext-R/G/B*	Vcc
0101011001010101	0x5655	00010000	GND	Open	GND
0101011001011001	0x5659	00010010	GND	Open	Rext-R/G/B*
0101011001100101	0x5665	00010100	GND	Open	Open
0101011001101001	0x5669	00010110	GND	Open	Vcc
0101011010010101	0x5695	00011000	GND	Vcc	GND
0101011010011001	0x5699	00011010	GND	Vcc	Rext-R/G/B*
0101011010100101	0x56A5	00011100	GND	Vcc	Open
0101011010101001	0x56A9	00011110	GND	Vcc	Vcc
0101100101010101	0x5955	00100000	Rext-R/G/B*	GND	GND
0101100101011001	0x5959	00100010	Rext-R/G/B*	GND	Rext-R/G/B*
0101100101100101	0x5965	00100100	Rext-R/G/B*	GND	Open
0101100101101001	0x5969	00100110	Rext-R/G/B*	GND	Vcc
0101100110010101	0x5995	00101000	Rext-R/G/B*	Rext-R/G/B*	GND
0101100110011001	0x5999	00101010	Rext-R/G/B*	Rext-R/G/B*	Rext-R/G/B*
0101100110100101	0x59A5	00101100	Rext-R/G/B*	Rext-R/G/B*	Open
0101100110101001	0x59A9	00101110	Rext-R/G/B*	Rext-R/G/B*	Vcc
0101101001010101	0x5A55	00110000	Rext-R/G/B*	Open	GND
0101101001011001	0x5A59	00110010	Rext-R/G/B*	Open	Rext-R/G/B*
0101101001100101	0x5A65	00110100	Rext-R/G/B*	Open	Open
0101101001101001	0x5A69	00110110	Rext-R/G/B*	Open	Vcc
0101101010010101	0x5A95	00111000	Rext-R/G/B*	Vcc	GND
0101101010011001	0x5A99	00111010	Rext-R/G/B*	Vcc	Rext-R/G/B*
0101101010100101	0x5AA5	00111100	Rext-R/G/B*	Vcc	Open
0101101010101001	0x5AA9	00111110	Rext-R/G/B*	Vcc	Vcc
0110010101010101	0x6555	01000000	Open	GND	GND
0110010101011001	0x6559	01000010	Open	GND	Rext-R/G/B*
0110010101100101	0x6565	01000100	Open	GND	Open
0110010101101001	0x6569	01000110	Open	GND	Vcc
0110010110010101	0x6595	01001000	Open	Rext-R/G/B*	GND
0110010110011001	0x6599	01001010	Open	Rext-R/G/B*	Rext-R/G/B*
0110010110100101	0x65A5	01001100	Open	Rext-R/G/B*	Open
0110010110101001	0x65A9	01001110	Open	Rext-R/G/B*	Vcc
0110011001010101	0x6655	01010000	Open	Open	GND
0110011001011001	0x6659	01010010	Open	Open	Rext-R/G/B*
0110011001100101	0x6665	01010100	Open	Open	Open
0110011001101001	0x6669	01010110	Open	Open	Vcc
0110011010010101	0x6695	01011000	Open	Vcc	GND
0110011010011001	0x6699	01011010	Open	Vcc	Rext-R/G/B*
0110011010100101	0x66A5	01011100	Open	Vcc	Open
011001101010101	0x66A9	01011110	Open	Vcc	Vcc
0110100101010101	0x6955	01100000	Vcc	GND	GND
3110100101010101	5,0555	3110000	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	5,12	5,15

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0110100101011001	0x6959	01100010	Vcc	GND	Rext-R/G/B*	
0110100101100101	0x6965	01100100	Vcc	GND	Open	
0110100101101001	0x6969	01100110	Vcc	GND	Vcc	
0110100110010101	0x6995	01101000	Vcc	Rext-R/G/B*	GND	
0110100110011001	0x6999	01101010	Vcc	Rext-R/G/B*	Rext-R/G/B*	
0110100110100101	0x69A5	01101100	Vcc	Rext-R/G/B*	Open	
0110100110101001	0x69A9	01101110	Vcc	Rext-R/G/B*	Vcc	
0110101001010101	0x6A55	01110000	Vcc	Open	GND	
0110101001011001	0x6A59	01110010	Vcc	Open	Rext-R/G/B*	
0110101001100101	0x6A65	01110100	Vcc	Open	Open	
0110101001101001	0x6A69	01110110	Vcc	Open	Vcc	
0110101010010101	0x6A95	01111000	Vcc	Vcc	GND	
0110101010011001	0x6A99	01111010	Vcc	Vcc	Rext-R/G/B*	
0110101010100101	0x6AA5	01111100	Vcc	Vcc	Open	
0110101010101001	0x6AA9	01111110	Vcc	Vcc	Vcc	
01XXXXXXXXXXXXX10	0x4002**	0XXXXXX1	All selections			

<sup>\*</sup> Please set it as a pin for one of Rext-R,G,B.

### b) Sub-address

Output channel setting/ All channels setting/ Special mode setting

In output channel setting, a channel which defines PWM configuration is selected. In all channels setting, PWM is configured for all channels. The special mode is the mode which sets all channels individually.

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Channel setting of	ommand	Original	Channel setting
Input with one wire	Hexadecimal	binary	
0101010101011001	0x5559	0000010	/OUTR0
0101010101100101	0x5565	00000100	/OUTG0
0101010101101001	0x5569	00000110	/OUTB0
0101010110010101	0x5595	00001000	/OUTR1
0101010110011001	0x5599	00001010	/OUTG1
0101010110100101	0x55A5	00001100	/OUTB1
0101010110101001	0x55A9	00001110	/OUTR2
0101011001010101	0x5655	00010000	/OUTG2
0101011001011001	0x5659	00010010	/OUTB2
0101100101010101	0x5955	00100000	All channels setting
0110100101010101	0x6955	01100000	Special mode setting

# c) Data byte (PWM dimming) Data bytes set PWM dimming.

PWM setting co	mmand	Original	PWM dimming
Input with one wire	Hexadecimal	binary	
0101010101010101	0x5555	00000000	0/127
0101010101011001	0x5559	00000010	1/127
0101010101100101	0x5565	00000100	2/127
***		•••	***
1010101010100101	0xAAA5	11111100	126/127
1010101010101001	0xAAA9	11111110	127/127

Notes) Any data other than those specified above must not be programed. Default setting is 0/127.

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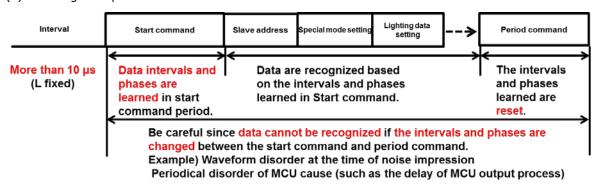
<sup>\*\*</sup> The hexadecimal number display of all selections is a case which is defined as x=0.

#### (5) Notes of data setting

This product has the specification of data recognition or processing with only a data signal (asynchronous input signal). The data period (communication speed) is read (learned) with the start command (data input start condition). Data are recognized according to this learning period, and reset the learning period with the period command (data input completion condition). Therefore, if the data period from the start command to the period command is collapsed, data are not recognized (see the following (a)).

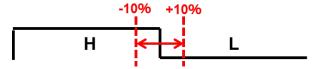
Moreover, if the duty rating is over  $\pm 10\%$  of H/L, data cannot be recognized. Make sure to set within  $\pm 10\%$ . (Refer to the following and operation ranges.)

#### (a) Learning data period



#### (b) Data recognition

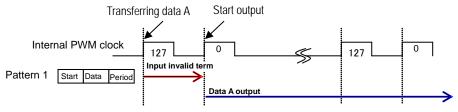
The duty of H/L pulse width to input to this product should be set within  $\pm 10\%$  as shown below. If the duty is out of this range, data cannot be recognized correctly (in the case that the modulation period is 100%).



If there is no reversal of data polarity in this window, data cannot be recognized.

### Reference: Example of control data input

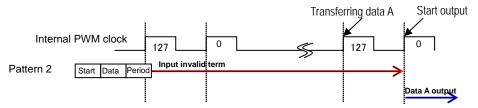
- (6) Example of data input to the same ID
  - a) In case data A is input up to the rising edge of 127 internal PWM clocks.



Output data A starts at the rising edge of zero internal PWM clock.

Inputting is invalid from the rising edge of 127 internal PWM clocks to the rising edge of zero internal PWM clock which is just after these 127 PWM clocks.

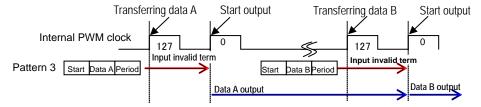
b) In case data A is input after the rising edge of 127 internal PWM clocks.



Outputting data A does not start at the rising edge of zero internal PWM clock just after the data A is input. It starts at the next rising edge of zero internal PWM clock.

Inputting is invalid from the data A (period) input to the rising edge of after the next zero internal PWM clock.

c) In case data B is input after data of pattern 1 starts outputting.



Outputting data A starts at the rising edge of zero internal PWM clock just after the data A is input. Outputting data B starts at the rising edge of zero internal PWM clock which is just after the data B input.

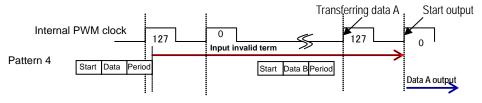
Inputting is invalid in the following term.

From the rising edge of 127 internal PWM clocks which are just after the data A is input to the rising edge of zero internal PWM clock which is just after these 127 clocks.

From the rising edge of 127 internal PWM clocks which is just after the data B input to the rising edge of zero internal PWM clock which is just after these 127 clocks.

Pay attention that the IC does not operate according to the configuration while the following patterns (patterns 4 and 5) are input.

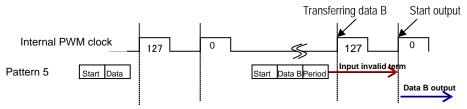
d) In case data B is input before starting the output of pattern 2.



Inputting is invalid from the data A (period) input to the rising edge of the second internal clock. So, data B is invalid and data A is output.

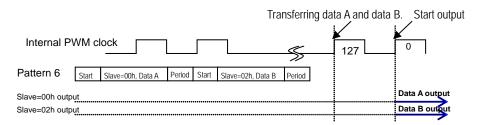


e) In case the period command mistakes.



Outputting data A does not start at the rising edge of zero internal clock which is just after the data A input. Outputting data B starts at the rising edge of zero internal PWM clock which is just after the data B input.

- (7) Example of data input to the different ID.
  - a) In case the data B is input to slave (= 02h) just after the data A is input to slave (= 00h).

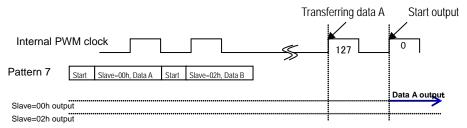


Both data A and data B are output at the rising edge of zero internal PWM clock which is just after the data A and the data B inputs.

Pay attention that the IC does not operate according to the configuration while following patterns (patterns 7 and 8) are input.

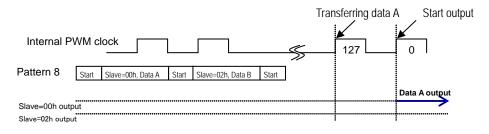
b) In case period command after inputting data A to the slave (=00h) is missed or omitted, or in case period command after inputting data B to the slave (=02h) is missed or omitted.

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Data A is output. Data B is not output.

c) In case start command is input after data B of pattern 7 is input.



Data A is output. Data B is not output.

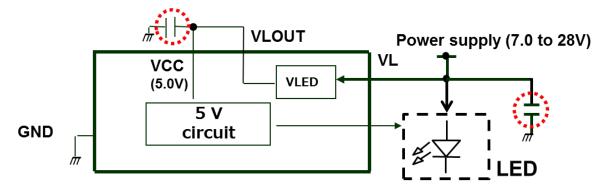
### **Power Supply Block**

The power supply of this product can be set with the following 2 ways shown in (1) and (2).

- (1) When the power supply of LEDs and those of this product are shared (The power supply function of this product is used.)
- (2) When this product is operated with 5V power supply input, not sharing the power supply of LEDs (The power supply function of this product is not used.)

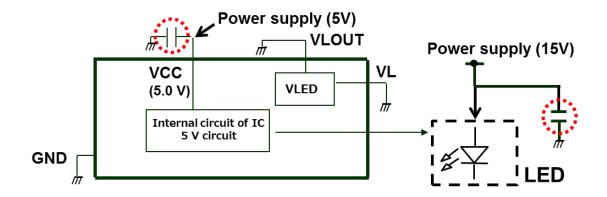
Each setting is shown below.

(1) When the power supply of LEDs and those of this product are shared



As shown in the above, the power supply (7.0 to 28V) is applied to the VL pin, and VLOUT and Vcc are connected directly. Connect VLOUT pin output (5V) to Vcc of own product, and also only 1 pcs of logic IC. (Do not connect with two or more logic ICs or other LED drivers.)

(2) When 5V power supply is input to Vcc directly



When 5V power supply is applied to this product without using the built-in power supply, ground VL pin and VLOUT pin.

#### Note)

Add decoupling capacitors to VL pin and Vcc pin. The recommended values are as follows.

Recommended value of decoupling capacitors between VL (LED power supply) and GND: 1 µF of electrolytic capacitor

\* Evaluate appropriately since it is dependent on the main power supply performance. Recommended value of decoupling capacitors between Vcc (5V power supply) and GND:  $1\mu$ F of electrolytic capacitor and  $0.1\mu$ F of ceramic capacitor

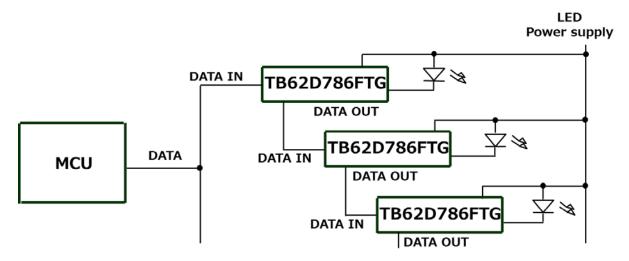
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\* Evaluate appropriately since it is dependent on the LED current to be set and current supply amount of VLOUT.

### **Data buffer**

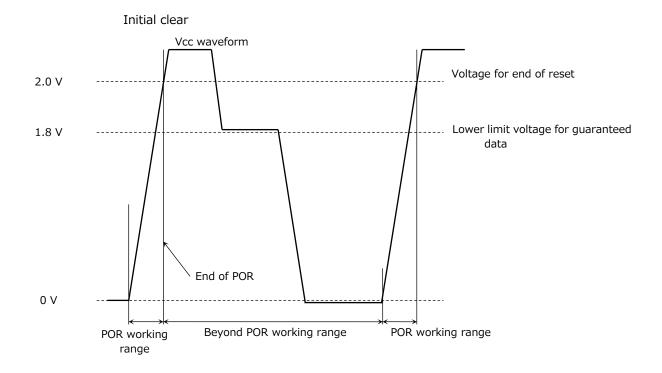
Data buffer is built in between DATA-IN and DATA-OUT, and it can be used for the cascade connection of two or more these products.

In the case of cascade connection with this buffer, connect up to 5 pieces on the same board.



### Power on reset (POR)

It avoids the malfunction by the reset all internal data of IC and setting default in startup. POR circuit operates only when VDD rises from 0 V. To restart POR, Vcc should be 0 V. As for the voltage for holding internal data, it is guaranteed after Vcc reaches 4.5 V or more once.



### Thermal shutdown function (TSD)

When the temperature of internal IC exceeds 150°C, all constant current outputs are turned off by this function. The constant current is output again when the temperature decreases to the rating.

TSD operation temperature 150°C to 180°C

TSD reset temperature -20°C from TSD operation temperature

### Notes of setting

#### Output load

This product is the driver in which loads are LEDs. Do not connect loads except LEDs to the output.

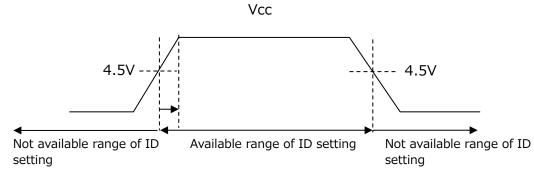
2. External resistor for LED drive current setting (Rext-R, Rext-G, Rext-B)

The external resistances to be connected to Rext-R, Rext-G, and Rext-B pins should be connected separately. Three resistances should not be shared as one resistance. The current error of each RGB may occur.

Operation sequence of ID setting

The ID setting can be available when VCC exceeds 4.5 V after turning on.

However, in order to prevent malfunction of the ID setting, the transitional input signals of less than 2-clock period of external input data (DATA-IN) are not received.



#### 4. Data setting

The gradation signals should be input data for 9 channels in the special mode certainly.

When the data are input to over 9 channels, the data after 10th channel are invalid.

When the data are input to less than 9 channels, the data of channels to be input are held, and the data of channels not to be input are held data before the input.

Moreover, do not input data which are not indicated in this document.

Confirm "Programming the TB62D786FTG" and "(5) Notes of data setting."

#### 5. Data setting timing

When data are input to same slave address, next data should be input with spacing the interval 3 ms or more (128 internal PWM clocks) because data may not be received.

When data are input to different slave address, the interval 3 ms (128 internal PWM clocks) or more is not required.

#### 6. Decoupling capacitor

For the stabilization of power supply system, it is recommended that decoupling capacitor between power supply and GND should place as near IC as possible. For details, refer to "power supply block."

<sup>\*</sup> TSD function aims at detecting abnormal heating of ICs. Please avoid positively using the TSD function.

### **State Transition Diagram**

<With VL pin>

VLOUT pin and VCC pin are wire-connected beforehand, and set each IC's ID (from ID0 to ID2 pin).

Turning on main power supply (VL pin)

VLOUT pin supplies IC operation voltage (4.5 V or more).

VCC pin voltage is 4.5V or more.

ID recognition

Data should be input after VCC voltage reaches 4.5V or more, and minimum 15ms passes.

#### **Normal mode**

The data of each output is updated for every ID set by the DATA signals, and LED illuminating is controlled.

More than TSD detecting

temperature

Less than TSD detecting temperature

### TSD (Thermal ShutDown) mode

All LED outputs are forced to OFF if the TSD detection temperature has reached.

<Without VL pin>

VLOUT pin and VL pin are wire-connected to GND beforehand, and set each IC's ID (from ID0 to ID2 pin).

Turning on IC power supply (VCC pin)

VCC pin voltage reaches 4.5V or more.

ID recognition

Data should be input after VCC voltage

reaches 4.5V or more, and minimum 15ms passes.

### **Normal mode**

The data of each output is updated for every ID set by the DATA signals, and LED illuminating is controlled.

More than TSD detecting

temperature

Less than TSD detecting temperature

### TSD (Thermal ShutDown) mode

All LED outputs are forced to OFF if the TSD detection temperature has reached.

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### Absolute Maximum Ratings (Ta=25°C)

Characteristics	Symbol	Rating	Unit
VL pin Supply Voltage	VL	29	V
Vcc pin Supply Voltage	Vcc	6.0	V
Input Voltage	V <sub>IN</sub>	-0.3 to Vcc + 0.3 *Note 1	V
Output Current	I <sub>OUT</sub>	85 *Note 4	mA/ch
Output Voltage	V <sub>OUT</sub>	-0.3 to 29	V
Power Dissipation	P <sub>d</sub>	2.4 *Note 2 and 3	W
Thermal resistance	R <sub>th (j-a)</sub>	51.5 *Note 2	°C/W
Operating Temperature Rating	T <sub>opr</sub>	-40 to 85	°C
Storage Temperature Rating	T <sub>stg</sub>	-55 to 150	°C
Maximum junction Temperature	Tj	150	°C

Note 1: Do not exceed 6.0 V.

Note 2: When mounted on a PCB( Board size:  $76.2\times114.3\times1.6$ mm, Cu=30%,  $35\mu m$  thick , SEMI Standard, 2-Layer)

Note 3: Power dissipation is reduced by 1/ Rth(j-a) for each °C above 25°C ambient.

Note 4: Current may be further restricted due to ambient temperature or board condition.

Ta: Ambient temperature of ICs

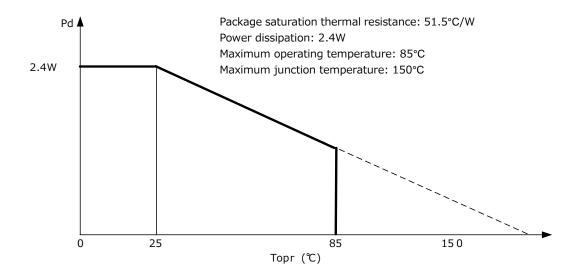
Topr: Ambient temperature of ICs to be operated

Tj: IC chip temperature during operating

For the design, it is recommended that the maximum of Tj is considered of the amount of use dissipation at about 120 °C.

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### **Power Dissipation**



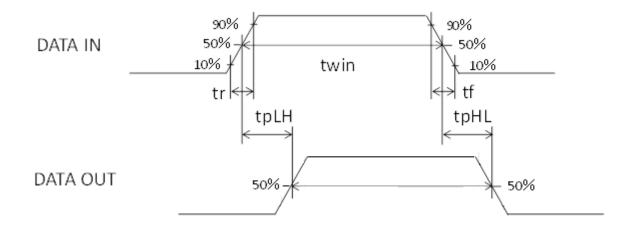
# Operating Ranges (T<sub>a</sub>=-40 to 85°C, unless otherwise specified)

Characteristics	Symbol	Test Condition	Min	Тур.	Max	Unit
VL pin Supply voltage	VL	-	7.0	-	28	V
Vcc pin supply voltage	Vcc	-	4.5	-	5.5	V
Output Voltage	V <sub>OUT</sub> (ON)	All outputs	0.5	-	4	V
Output Current	I <sub>OUT</sub>	All outputs	5	-	40	mA/ch
Input DATA Frequency	Fin		0.5	-	2.0	MHz
Input DATA Duty	Fin(duty)		40	50	60	%
	V <sub>IH</sub>	DATA-IN	0.7 × Vcc	-	Vcc	
	V <sub>IL</sub>	DATA-IN	GND	-	0.3 × Vcc	
Input Voltage	V <sub>ID0</sub>		0	-	0.1	V
	V <sub>ID1</sub>	ID0, ID1, ID2	VRext -0.1	VRext	VRext +0.1	
	V <sub>ID2</sub>		Vcc - 0.1	-	Vcc	
VLOUT load current	ΔVI	Except Supply current	-	-	15	mA

# Electrical Characteristics ( $T_a$ =25°C, VL=15V, VCC=VLOUT, Unless otherwise specified )

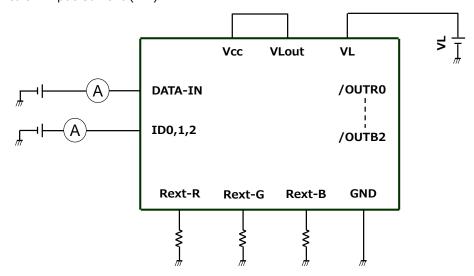
Characteristics	Symbol	Test Condition	Min	Тур.	Max	Unit	
Output Current	I <sub>OUT1</sub>	$V_{OUT} = 0.5V$ , R-EXT = $1.2k\Omega$	12.5	13.3	14.1	mA	
Output Current Accurcy between channels	ΔI <sub>OUT2</sub>	$V_{OUT}$ = 0.5V, R-EXT =1.2k $\Omega$ All output ON	-	-	±3.0	%	
Output leakage current	I <sub>OZ</sub>	V <sub>OUT</sub> = 28 V	-	-	1	μΑ	
VLout pin voltage	VLout		4.5	-	5.5	V	
Input current	I <sub>IH</sub>	DATAIN	-	-	1	μА	
	I <sub>IL</sub>	DATAIN	-	-	-1		
	I <sub>ID</sub>	ID0, ID1, ID2	-	-	±10		
Changes in constant output current dependent on Vcc	%/Vcc	Vcc = 4.5 V to 5.5 V	-	1	2	%	
	Icc (VL)	When applied VL=15 V R-EXT =1.2k $\Omega$ , V <sub>OUT</sub> =0.5V,	-	7.8	15	_	
Supply Current	Icc (Vcc)	When connected VL=GND R-EXT =1.2k $\Omega$ , V <sub>OUT</sub> =0.5V,	-	7.4	12	mA	
H Level DATA OUT Pin Output Voltage	VOH	IOH= -1mA	Vcc -0.4	-	-	٧	
L Level DATA OUT Pin Output Voltage	VOL	IOL= 1mA	-	-	0.4	V	
DATAIN-DATAOUT	tpLH	Cl _1EnE +r_+f_2na	-	-	20	20	
Propagation Delay Time *1	tpHL	CL=15pF, tr=tf=3ns pHL		-	20	ns	

### (\*1) DATA IN - DATA OUT definition

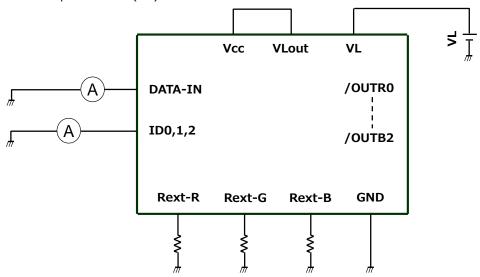


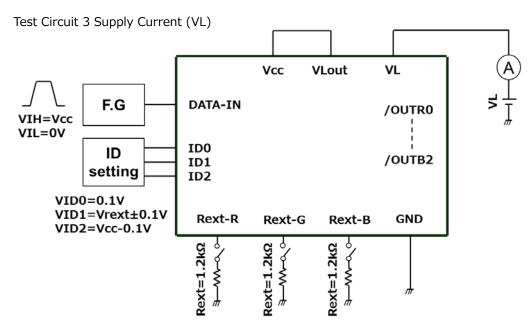
### **Test Circuit**

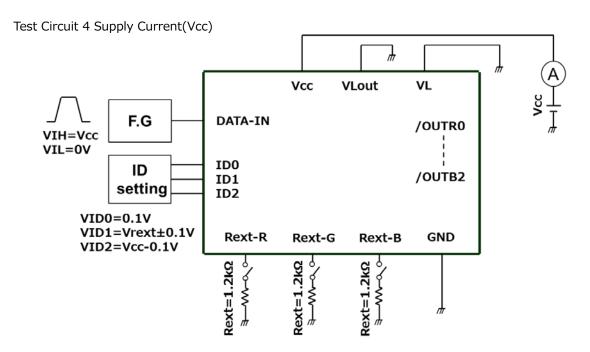
Test Circuit 1 Input Current (IIH)



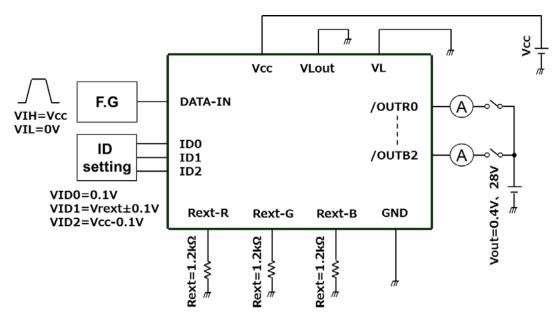
Test Circuit 2 Input Current (IIL)





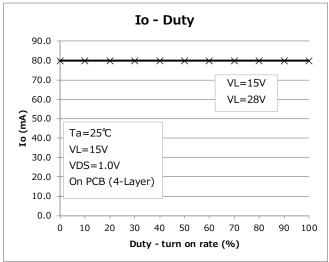


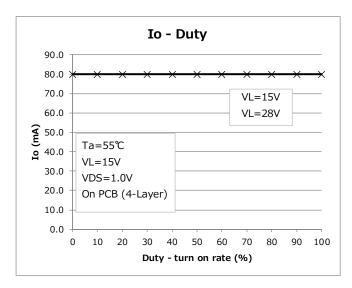
Test Circuit5 Output Current/ Output Leakage Current/ Output Current Accuracy/ Changes in Constant Output current dependent on Vcc

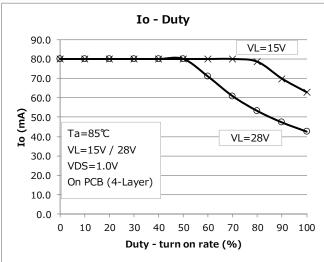


### Output current - derating (illuminating rate) graph

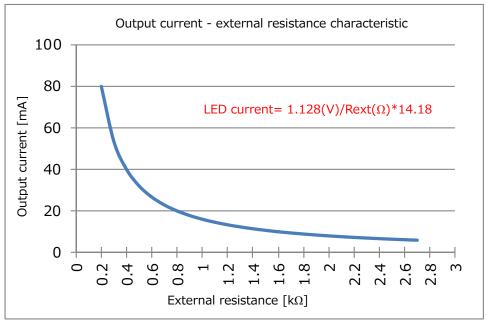
Board condition:  $76.2 \times 114.3 \times 1.6$  mm, Cu=30%,  $35\mu m$  thickness, compliant with SEMI When the pulse width is 25 ms or more, it is regarded as DC.



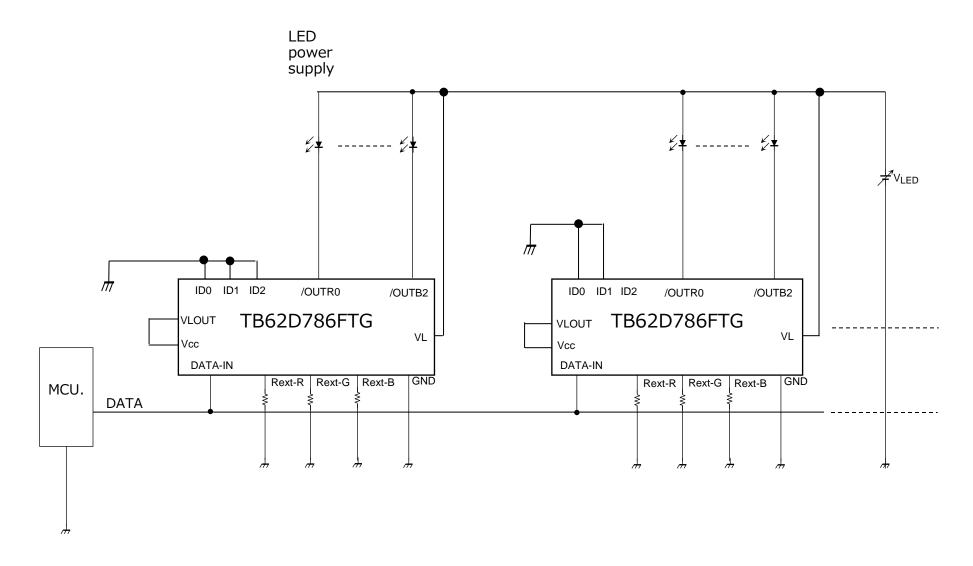




### Output current - external resistance characteristic



# Application circuit example 1



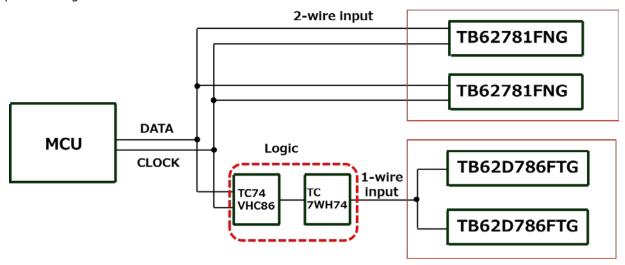
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### **Application circuit example 2**

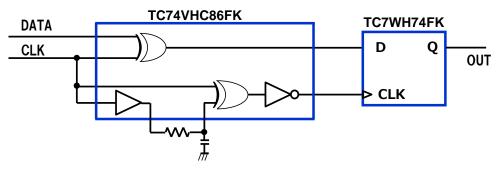
When this product is controlled from same MCU ports of TB62781FNG, which is 2-wire input control LED driver, need to connect the Exclusive-OR gate (TC74VHC86) and D-Flip/Flop to preceding phase of the input of this product as shown below.

Since phase differences between DATA from MCU outputting and clock may occur, confirm the operation enough with the following configuration.

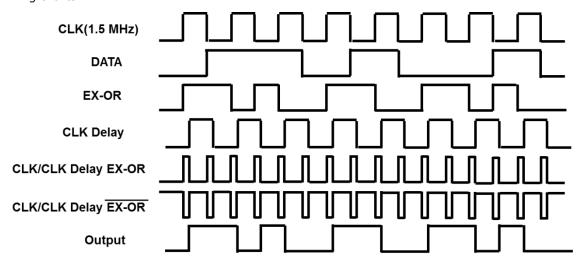
### -System configuration



#### -Logic



#### -Timing charts

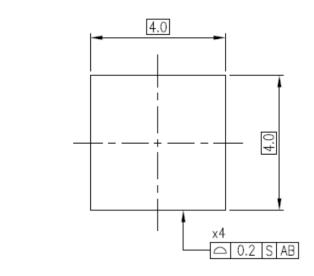


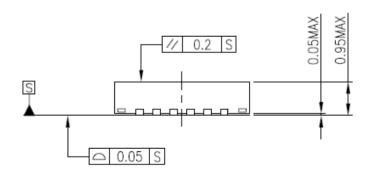
### **Package Dimensions**

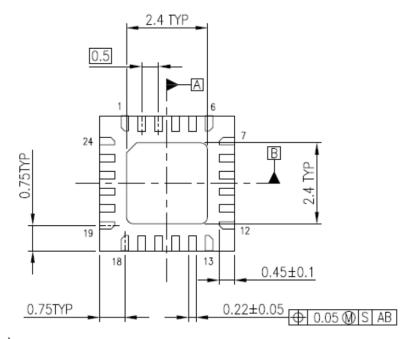
**TOSHIBA** 

### P-VQFN24-0404-0.50-001

Unit: mm







Weight: 0.037g (Typ.)

### **Notes of Contents**

### 1. Block diagram

Some of the functional blocks, circuits, or constants in the block diagram may be omitted or simplified for explanatory purposes.

#### 2. Equivalent circuits

The equivalent circuit diagrams may be simplified or some parts of them may be omitted for explanatory purposes.

### 3. Timing charts

Timing charts may be simplified for explanatory purposes.

### 4. Application circuit example

The application circuit examples shown in this document are provided for reference purposes only. Thorough evaluation is required, especially at the mass production design stage. Toshiba does not grant any license to any industrial property rights by providing these examples of application circuits.

#### 5. Test circuits

Components in the test circuits are used only to obtain and confirm the device characteristics. These components and circuits are not guaranteed to prevent malfunction or failure from occurring in the application equipment.

### **IC Usage Considerations**

### Notes on handling of ICs

- (1) The absolute maximum ratings of a semiconductor device are a set of ratings that must not be exceeded, even for a moment. Do not exceed any of these ratings.
  Exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion.
- (2) Use an appropriate power supply fuse to ensure that a large current does not continuously flow in case of over current and/or IC failure. The IC will fully break down when used under conditions that exceed its absolute maximum ratings, when the wiring is routed improperly or when an abnormal pulse noise occurs from the wiring or load, causing a large current to continuously flow and the breakdown can lead smoke or ignition. To minimize the effects of the flow of a large current in case of breakdown, appropriate settings, such as fuse capacity, fusing time and insertion circuit location, are required.
- (3) If your design includes an inductive load such as a motor coil, incorporate a protection circuit into the design to prevent device malfunction or breakdown caused by the current resulting from the inrush current at power ON or the negative current resulting from the back electromotive force at power OFF. IC breakdown may cause injury, smoke or ignition. Use a stable power supply with ICs with built-in protection functions. If the power supply is unstable, the protection function may not operate, causing IC breakdown. IC breakdown may cause injury, smoke or ignition.
- (4) Do not insert devices in the wrong orientation or incorrectly. Make sure that the positive and negative pins of power supplies are connected properly. Otherwise, the current or power consumption may exceed the absolute maximum rating, and exceeding the rating(s) may cause the device breakdown, damage or deterioration, and may result injury by explosion or combustion. In addition, do not use any device that is applied the current with inserting in the wrong orientation or incorrectly even just one time.
- (5) Carefully select external components (such as inputs and negative feedback capacitors) and load components (such as speakers), for example, power amp and regulator.

  If there is a large amount of leakage current such as input or negative feedback condenser, the IC output DC voltage will increase. If this output voltage is connected to a speaker with low input withstand voltage, overcurrent or IC failure can cause smoke or ignition. (The over current can cause smoke or ignition from the IC itself.) In particular, please pay attention when using a Bridge Tied Load (BTL) connection type IC that inputs output DC voltage to a speaker directly.



### Points to remember on handling of ICs

#### (1) Heat Radiation Design

In using an IC with large current flow such as power amp, regulator or driver, please design the device so that heat is appropriately radiated, not to exceed the specified junction temperature (Tj) at any time and condition. These ICs generate heat even during normal use. An inadequate IC heat radiation design can lead to decrease in IC life, deterioration of IC characteristics or IC breakdown. In addition, please design the device taking into considerate the effect of IC heat radiation with peripheral components.

#### (2) Back-EMF

When a motor rotates in the reverse direction, stops or slows down abruptly, a current flow back to the motor's power supply due to the effect of back-EMF. If the current sink capability of the power supply is small, the device's motor power supply and output pins might be exposed to conditions beyond absolute maximum ratings. To avoid this problem, take the effect of back-EMF into consideration in system design.

### (3) Thermal Shutdown Circuit

Thermal shutdown circuits do not necessarily protect ICs under all circumstances. If the thermal shutdown circuits operate against the over temperature, clear the heat generation status immediately. Depending on the method of use and usage conditions, such as exceeding absolute maximum ratings can cause the thermal shutdown circuit to not operate properly or IC breakdown before operation.

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