



A Product Line of Diodes Incorporated



## Description

The AP1685 is a high performance AC/DC power factor corrector for mains dimmable LED driver applications. The device uses Pulse Frequency Modulation (PFM) technology to regulate output current while achieving high power factor and low THD. It operates as a BCM (Boundary Conduction Mode) which is good for EMI.

The AP1685 internally integrates a 500V high voltage MOSFET which can realize a lower BOM cost. The AP1685 provides accurate constant current (CC) regulation while removing the opto-coupler and secondary control circuitry. It also eliminates the need of loop compensation circuitry while maintaining stability. It can meet the requirement of IEC6100-3-2 harmonic standard.

The AP1685 features low start-up current, low operation current. It adopts valley on switching mode to achieve high efficiency. It also has rich protection features including over voltage, short circuit, over temperature protection.

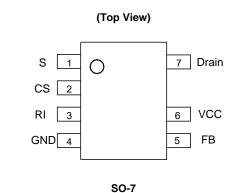
The AP1685 is available in SO-7 package.

## Applications

Non-dimmable LED drivers

## OFFLINE, HIGH PF, HIGH EFFICIENCY LED DRIVER IC

## **Pin Assignments**



#### Features

- Boundary Conduction Mode (BCM) Operation to Achieve Highefficiency
- High PF and Low THD (PF>0.9, THD<30%)
- High Efficiency
- Low Start-up Current
- Tight LED Current
- Tight LED Open Voltage
- Valley-mode Switching to Minimize the Transition Loss
- Internal Integrated 2.5A/500V MOSFET can Cover up to 10W
- Easy EMI
- Internal Protections:
  - Under Voltage Lock Out (UVLO)
  - Leading-edge Blanking (LEB)
  - Output Short Protection
  - Output Open Protection
  - Over Temperature Protection
- Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)
- Halogen and Antimony Free. "Green" Device (Note 3)

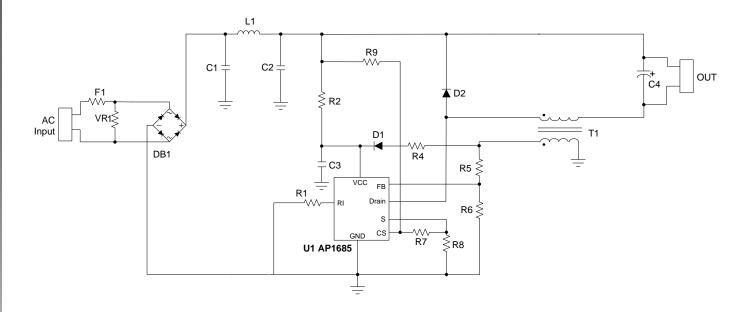
Notes: 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS) & 2011/65/EU (RoHS 2) compliant.

- 2. See http://www.diodes.com/quality/lead\_free.html for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
- 3. Halogen- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.

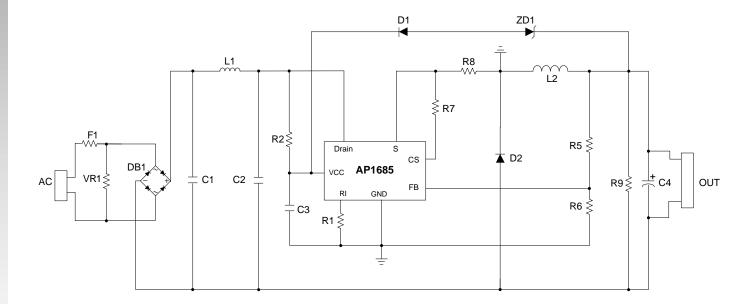




# **Typical Applications Circuit**



#### Typical Buck Application with Auxiliary Winding



#### Typical Floating Buck Application without Auxiliary Winding

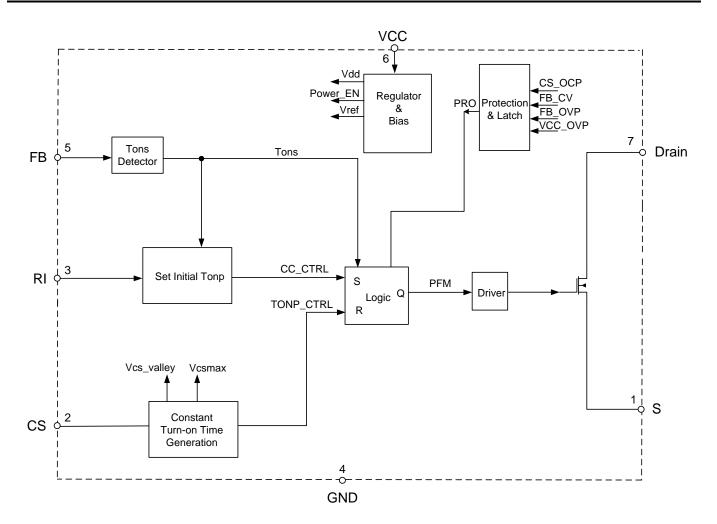




# **Pin Descriptions**

Pin Number	Pin Name	Function		
1	S	Internal MOSFET's Source		
2	CS	Current sensing		
3	RI	Setting the initial on time		
4	GND	Ground		
5	FB	The feedback voltage from auxiliary winding		
6	VCC	Supply voltage of gate driver and control circuits of the IC.		
7	Drain	Internal MOSFET's Drain		

# **Functional Block Diagram**







## Absolute Maximum Ratings (Note 4) (@T<sub>A</sub> = +25°C, unless otherwise specified.)

Symbol	Parameter	Rating	Unit
V <sub>CC</sub>	Power Supply Voltage	-0.3 to 35	V
V <sub>CS</sub>	Voltage at CS to GND	-0.3 to 7	V
V <sub>FB</sub>	FB Input Voltage	-40 to 10	V
V <sub>Drain</sub>	Voltage on Drain	500	V
Ι <sub>D</sub>	Continue Drain Current $T_C = +25^{\circ}C$	2.5	А
TJ	Operating Junction Temperature	-40 to +150	°C
T <sub>STG</sub>	Storage Temperature	-65 to +150	°C
T <sub>LEAD</sub>	Lead Temperature (Soldering, 10 sec)	+300	°C
PD	Power Dissipation ( $T_A = +50^{\circ}C$ )	0.65	W
θ <sub>JA</sub>	Thermal Resistance (Junction to Ambient)	160	°C/W
_	ESD (Human Body Model)	±2000	V
_	ESD (Machine Model)	±200	V

Note 4: Stresses greater than those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "Recommended Operating Conditions" is not implied. Exposure to "Absolute Maximum Ratings" for extended periods may affect device reliability.

# **Recommended Operating Conditions**

Symbol	Parameter	Min	Мах	Unit
V <sub>CC</sub>	Power Supply Voltage	8	25	V
T <sub>A</sub>	Ambient Temperature	-40	+105	°C





# Electrical Characteristics (@T<sub>A</sub> = +25°C, unless otherwise specified.)

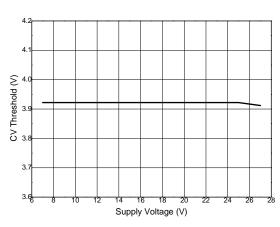
Symbol	Parameter	Conditions	Min	Тур	Max	Unit
UVLO Section		Conditions		196	mux	Unit
			13		10	
V <sub>TH</sub> (ST)	Start-up Threshold			14.5	16	V
V <sub>OPR</sub> (Min)	Minimum Operating Voltage	After turn on	5.5	6.5	7.5	V
Vcc_ovp	VCC OVP Voltage	-	27	29	31	V
_	VCC Delatch Voltage (Note 5)	-	3	4	5	V
Standby Current Section	n					
Ist	Start-up Current	$V_{CC} = V_{TH} (ST)-0.5V,$ Before start up	_	_	20	μA
I <sub>CC</sub> (OPR)	Operating Current	Static	-	900	1300	μA
Current Sense Section						
Vcs_ref	V <sub>CS_REF</sub> Current Sense Reference		_	1	_	V
V <sub>CS_CLAMP</sub>	Current Sense Reference Clamp	-	1.2	1.4	-	V
t <sub>ONP_MIN</sub>	Minimum t <sub>ONP</sub>	-	700	-	1000	ns
t <sub>D(H-L)</sub>	Delay to Output (Note 5)	-	50	150	250	ns
Feedback Input Section						
I <sub>FB</sub>	Feedback Pin Input Leakage Current	V <sub>FB</sub> = 2V	_	_	4	μΑ
$V_{FB_CV}$	FB CV Threshold	_	3.8	4	4.2	V
V <sub>FB_OVP</sub>	FB OVP Threshold	-	4.5	6	7.5	V
Internal MOSFET Sectio	n				•	
Rds(on)	Drain-Source On-State Resistance	$V_{GS} = 10V, I_D = 1.25A$	_	_	6	Ω
V <sub>BR(Drain)</sub>	Drain-Source Breakdown Voltage	$V_{GS} = 0V, I_D = 250 \mu A$	500	_	_	V
I <sub>DSS</sub>	Drain-Source Leakage Current	$V_{DS} = 500V, V_{GS} = 0V$	_	-	1	μA
Output Current						
_	System Output Current On Final Test Board	_	_	-	±2	%
Over Temperature Prote	ection Section					
_	Shutdown Temperature (Note 5)	-	+150	-	-	°C
_	Temperature Hysteresis (Note 5)	_	_	+20	_	°C

Note 5: These parameters, although guaranteed by design, are not 100% tested in production.



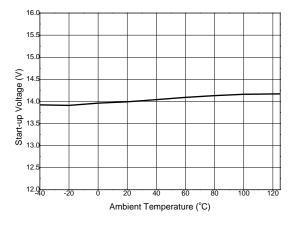
AP1685

# **Performance Characteristics**

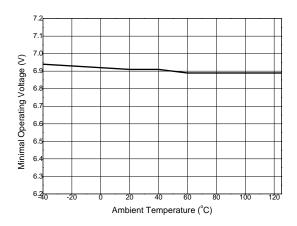


## CV Threshold vs. Supply Voltage

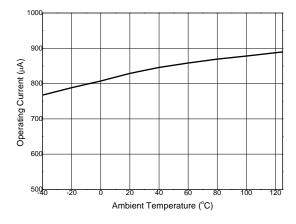
Start-up Voltage vs. Ambient Temperature



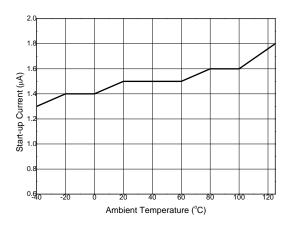
#### Minimal Operating Voltage vs. Ambient Temperature



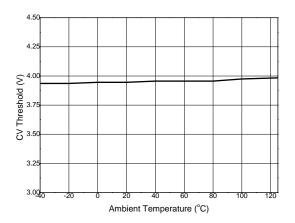
#### **Operating Current vs. Ambient Temperature**



Start-up Current vs. Ambient Temperature



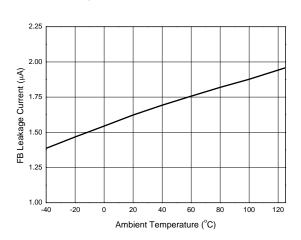
#### CV Threshold vs. Ambient Temperature





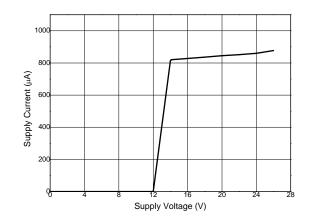


# Performance Characteristics (Cont.)



### FB Leakage Current vs. Ambient Temperature

Supply Current vs. Supply Voltage





AP1685

# Application Information

The AP1685 is designed for single voltage application, and it features high power factor correction (PFC), low total harmonic distortion (THD), low BOM cost and good EMI performance. The device can be widely used in non-dimmable LED application such as GU10, bulb lamps, down lamp, etc. The AP1685 adopts constant on time control method within one AC cycle to achieve the high power factor and low THD. The control scheme is very simple, the power factor correction effectiveness is obvious, and the constant current control is also good enough.

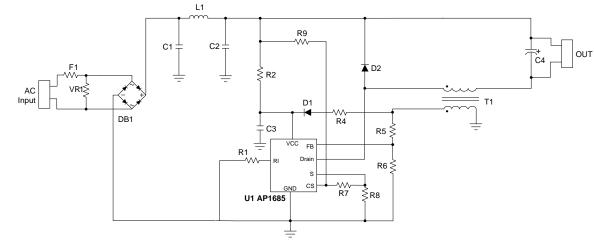


Figure 1. Typical Application Circuit

## Design Parameters

#### Setting the Current Sense Resistor R8

As the AP1685 adopts constant on time control method, the current of the inductance will follow the input voltage to get a sinusoidal wave. The current sense pin CS of the AP1685 will sense the peak current of the inductance by sensing the voltage dropped on the current sense resistor R8, and the constant current control is realized by controlling the peak current. In buck structure, when the  $V_0$  is higher than  $V_{IN}$ , no energy will be transferred from input to output which is called dead zone, and considering the dead zone of buck structure, the output current can be calculated as below:

$$I_{o\_mean} = k \cdot \frac{1}{\pi} \cdot \frac{V_{cs\_ref}}{R8}$$

Where,

 $V_{cs\_ref}$  is the reference of the current sense, and the typical value is 1V.

k is the current modification coefficient, and the value of k is approximate to be 0.7.

So, the current sense resistor R8 is determined:

$$R8 = k \cdot \frac{V_{cs\_ref}}{\pi \cdot I_{o\_mean}}$$

#### Transformer Selection (T1)

The non-isolated buck circuit in Figure 1 is usually selected, and the system is operating at boundary conduction mode. The system's operating frequency does not keep constant, the minimum switching frequency at the crest is set as f<sub>min</sub>, and then the buck inductance value L can be got:

$$L = \frac{(\sqrt{2} \cdot V_{in\_rms} - V_o) \cdot R8 \cdot V_o}{V_{cs\_ref} \cdot \sqrt{2} \cdot V_{in\_rms} \cdot f_{\min}}$$

Where,

Vo is the output voltage.

Vin\_rms is the RMS value of the input voltage.





## Application Information (Cont.)

The next step is determining the transformer's winding turns number, the worst case operation condition of transformer is at the peak voltage area of sine waveform input voltage where the current of across the inductance is the maximum value. The transformer design should be based on the worst case operation condition to guarantee that the transformer is not saturated. According to Ferrari's law of electromagnetic induction, the winding turns number of the buck inductance  $N_L$  is:

$$N_L = \frac{L \cdot I_{pk}}{A_e \cdot B_m} = \frac{L \cdot V_{cs\_ref}}{A_e \cdot B_m \cdot R8}$$

Where,

 $A_e$  is the core effective area.

B<sub>m</sub> is the maximum magnetic flux density.

The auxiliary winding is power supply for  $V_{CC}$ , the winding turns number  $N_{aux}$  is:

$$N_{aux} = N_L \cdot \frac{V_{cc}}{V_o + V_d}$$

Where,

V<sub>CC</sub> is the power supply voltage for IC from auxiliary winding.

 $V_{\text{d}}$  is the voltage drop of the freewheel diode.

#### Setting the Initial On Time

As the AP1685 adopts constant on-time control method, the AP1685 will generate an initial on time to start a working cycle. If the initial on time is longer than the rated on time, overshoot will happen which could damage the LED. And a good system performance does not permit overshoot, so the appropriate initial on time should be guaranteed. And initial on time is determined by resister R1 shown in Figure 1.

According to initial on time generation mechanism, the ton\_initial is

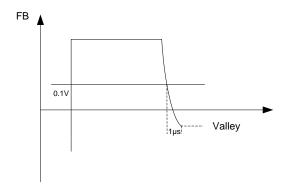
$$t_{on\_initial} = 80 \cdot R1 \cdot 10^{-12} s$$

To guarantee the system with no overshoot phenomenon, the resistor is selected

$$R1 = \frac{1.25 \cdot L}{R8 \cdot \sqrt{2}U_{in\_rms\_max}} \cdot 10^{10} \Omega$$

#### Valley on Control Method

The valley on function can provide low turn-on switching losses for buck converter. The voltage across the drain and source of the power MOSFET is reflected by the auxiliary winding of the buck transformer. The voltage is sensed by the FB pin.









## Application Information (Cont.)

According to Figure 2, when the falling edge of 0.1V is sensed by the FB pin, the AP1685 will see the t<sub>OFF</sub> time is over and delay 1µs to start a new operating cycle. In this way we can realize valley on function.

#### Fault Protection

**Over Voltage Protection and Output Open Protection** 

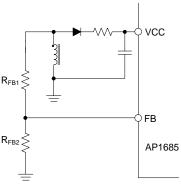


Figure 3. OVP Circuit

The output voltage is sensed by the auxiliary winding voltage of the buck transformer, the VCC pin and FB pin provide over voltage protection function. When the output is open or large transient happens, the output voltage will exceed the rated value. When the voltage of  $V_{CC}$  cap exceeds  $V_{CC_{ovp}}$  or  $V_{FB_{CV}}$ , the over voltage is triggered and the IC will discharge  $V_{CC}$ . When the  $V_{CC}$  is below the UVLO threshold voltage, the IC will start a new work cycle and the  $V_{CC}$  cap is charged again by start resistance. If the over voltage condition still exists, the system will work in hiccup mode.

#### **Output Short Protection**

When the output is shorted, the output voltage will be clamped at 0. At this condition,  $V_{CC}$  will drop down without auxiliary winding for power supply. And the  $V_{CC}$  will drop to UVLO threshold voltage, the IC will shut down and restart a new operating cycle, and the  $V_{CC}$  is charged by startup resistance. When the  $V_{CC}$  is higher than  $V_{cc\_start}$  voltage, the IC will output a bunch of pulse to control power MOSFET on and off, which will consume the energy stored in the  $V_{CC}$  cap, because of no  $V_{CC}$  supply from the auxiliary winding, the  $V_{CC}$  will drop down to  $V_{CC}$  UVLO threshold voltage again. If output short condition still exists, the system will operate in hiccup mode.

#### Over Temperature Protection

The AP1685 has two kinds of over temperature protection processes. First, the system is operating normally, the ambient temperature is changed to +170°C suddenly, the IC will trigger over temperature protection which leads to a latch work mode. Second, if the system starts, the over temperature protection will be triggered when the ambient temperature is higher than +150°C. So the AP1685 can startup successfully when the ambient temperature is less than +150°C.

#### **Recommended Applications**

The AP1685 is a device which internally integrates a MOSFET, the output current is limited by the internal integrated MOSFET, using this device can cover up to 10W's application meanwhile the output current is less than 200mA.

#### **Components Selection Guide**

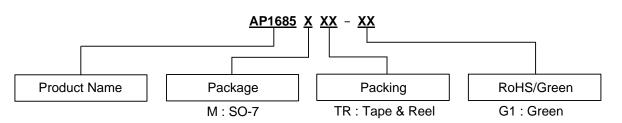
If the system's output spec is changed, please refer to the design sheet of the AP1685 and select the compatible system parameter. When the system needs to be adjusted slightly, please refer to the table below and adjust the value of the related component.

Item	Description	Related Components
lo	LED current	R8
Output Current Ripple	Small current ripple is good for LED life	C4
t <sub>on_initial</sub>	System initial on time, used to start up the system	R1
Output Open Voltage	Setting the output voltage when the LED is open	R5, R6
Line Compensation	To get a good line regulation	R7, R9
Startup Time	System startup time	R2, C3, T1
EMI	Pass EN 55022 class B with 6DB margin	L1, C1, C2





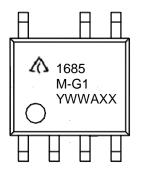
# **Ordering Information**



Package	Temperature Range	Part Number	Marking ID	Packing	
SO-7	-40°C to +105°C	AP1685MTR-G1	1685M-G1	4000/13"Tape & Reel	

# **Marking Information**

(Top View)



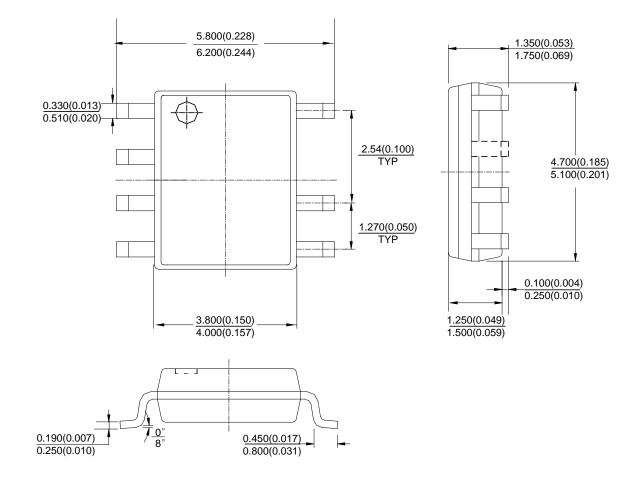
First and Second Lines: Logo and Marking ID Third Line: Date Code Y: Year WW: Work Week of Molding A: Assembly House Code XX: 7<sup>th</sup> and 8<sup>th</sup> Digits of Batch No.





# Package Outline Dimensions (All dimensions in mm (inch).)

#### (1) Package Type: SO-7



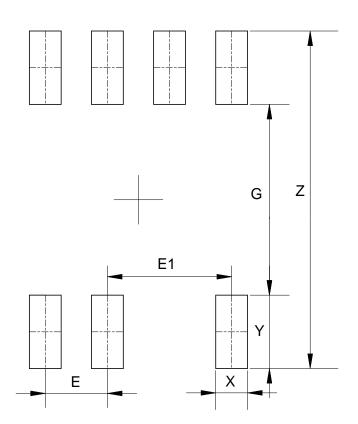
Note: Eject hole, oriented hole and mold mark is optional.





# **Suggested Pad Layout**

## (1) Package Type: SO-7



Dimensions	Z	G	X	Y	E	E1
	(mm)/(inch)	(mm)/(inch)	(mm)/(inch)	(mm)/(inch)	(mm)/(inch)	(mm)/(inch)
Value	6.900/0.272	3.900/0.154	0.650/0.026	1.500/0.059	1.270/0.050	2.540/0.100





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